

Software and Hardware for Land Development Professionals



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Carlson Software produces a complete suite of solutions for land development professionals, across the disciplines of data collection, surveying, engineering design and drafting. In addition, utilizing its expertise in data collection, Carlson also offers accident and crime reconstruction field and office software for law enforcement personnel or law consultants.

 We at Carlson recognize the paramount importance of free choice to the professional consumer in the land industry. We are committed to providing consistent software interfaces across hardware and across disciplines. This is the mission of Carlson Software.

> --R. Bruce Carlson Founder and President Carlson Software

Founded in 1983 and based in Maysville, Kentucky, U.S.A., Carlson has a branch office in Boston, Massachusetts, U.S.A., and local representatives in Australia, Russia, Germany, The Netherlands, Spain, Ireland, and El Salvador.



#### CLASS 1 **ASER PRODUC**

The Carlson C-ALS laser system provides safe, quick, and reliable mapping capabilities for inaccessible underground cavities. Deployable via boreholes on cable or rods, via a boom, or on a zip-wire, the C-ALS system can be used from the surface to provide a detailed visual record of the subsurface environment in a wide range of applications. A C-ALS Gyro option now gives greater navigational capability, ensuring that the probe's position along the borehole can be determined without relying on the mechanical alignment of deployment rods or a magnetic compass.

# **C-ALS supports successful projects**

The Carlson C-ALS system enables laser scanning of air-filled voids to create geo-referenced 3D models of subsurface conditions as a cost-effective. comprehensive, and accurate alternative to systematic drilling, enabling users to:

- Protect worker safety
- Report to project stakeholders in greater detail .
- Cost out planned works accurately .
- Devise more efficient work programs .
- Move new projects forward faster .
- Design and engineer solutions based on accurate data .
- . Minimize disruption, drilling, and disturbance in populated areas

# The advantages of C-ALS laser scanning

- Ability to survey potentially dangerous underground voids safely •
- Get precise and accurate cavity/void measurement in minutes, not days •
- 360° spherical coverage for a full view from a single scan, with no blind spots .
- Operation is remotely controlled .
- Deployment methods are flexible .
- . Easily transported
- Rugged design for durability in extreme conditions -•
  - IP67 rating (probe only)
  - Withstands submersion to a depth of 1 m (in case accidentally deployed in a flooded cavity)
  - Withstands extremes of temperature and high humidity

# How it works

- With a diameter of just 50 mm, the Carlson C-ALS system is easily deployed through boreholes, downhole or uphole in order to survey inaccessible spaces.
- A system of hinged, lightweight, 1 m rods provide a fixed azimuth capability, as well as the ability to deploy the C-ALS down boreholes as long as 200 m.
- The C-ALS probe incorporates pitch-and-roll sensors. The sensors ensure C-ALS can be tracked both up and down the borehole and that the scan is automatically georeferenced to fit into existing 3D mine data.
- Alternatively, the C-ALS Gyro uses an internal MEMS IMU to establish the heading ٠ and inclination of the probe as it is deployed. An initial reference azimuth is determined on the surface and the survey is then relative to this heading. This gives the possibillity of more flexible, cable-only deployments.
- A nosecone camera, embedded within the end of the C-ALS probe, provides onscreen video and a real-time view of the borehole as the probe is deployed. This allows operators to see any obstructions, and judge the point at which the C-ALS scanning head and rotating horizontal shaft breaks through into the void.
- Once in the void, a simple click from the operator commands the laser-scanning head to rotate on two axes, measuring the 3D shape of the void with full (horizontal axis) 360° coverage and no blind spots, and with a range up to 150 m.
- Operators control C-ALS from a distance, via the robust PC or tablet that may • be optionally included in the package. PC or tablet is linked to the C-ALS system by Ethernet cable or a WiFi link. From a safe distance, the operator can view live data, analyse point clouds and create models.







The C-ALS system deployed The nosecone camera pro- The probe rotates on two downhole to survey an inac- vides a helpful view into the axes to create full 360-degree cessible underground void. borehole during deployment. scans of voids and cavities.

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# Monitor excavations, assess risk, or design solutions

Utilize the Carlson C-ALS system when a complete picture of the situation underground is needed. Identify, measure, and map voids below construction or geo-technical projects to help avoid/prepare for differential settlement, sinkholes, or even catastrophic collapse of old mine workings or voids that may underlie residential and commercial properties. With the complete picture the C-ALS system provides, engineering solutions can then be put into place to counter the problems.

The C-ALS system can be used in a huge range of applications where an inaccessible void exists and accurate data is required.

# **C-ALS Gyro option**

C-ALS units are available with a fitted, miniaturised MEMS IMU. The IMU contains a 3-axis gyro which monitors the probe's heading and accelerometers which determine the inclination. In this case, the lightweight rods are not required for their original purpose of mechanically aligning the probe during a deployment. The rods may still be useful to push the probe along horizontal or uphole deployments, or to retain stability during free-hanging deployments. In other cases, with the gyro active, the C-ALS can be lowered just with its cable, or with the addition of a manual or powered winch.

Prior to a deployment, the C-ALS Gyro probe is set out in a stable position and its heading is established in relation to the mine's grid system. This forms the reference orientation for the rest of the deployment.

The software automatically identifies the gyro & offers controls appropriate to this variety of C-ALS.

# Support underground or surface mining projects

By using C-ALS to determine the size, extent, and status of inaccessible voids, mining customers get a complete picture of the situation underground before committing to projects or deploying workers. In addition, a full understanding of the layout of underground workings and their relation to surface operations is also essential for safe open-pit operations using heavy machinery, explosives, and personnel.

The C-ALS system provides a detailed visual record of the following:

- Excavation and infill of stopes
- Location of voids
- Geometry and condition of mine workings
- Inaccessible historic workings
- Collapsed areas, sinkholes, and troughs
- Erosion of ore passes
- Volumes of voids
- Position of cavities in relation to other underground workings and structures
- Size and location of remaining pillars
- Location of the voids/workings relative to surface features





The ruggedised PC enables you to carry out operations on site in extreme environments.



Laser cavity scans are easy to export into a large range of software packages.

# **Carlson Scan software**

Carlson's software for C-ALS makes it easier and quicker for operators to use the system, to analyse collected data and to produce industry-standard deliverables.

- Quick navigation and intuitive design for both new and experienced operators.
- Smooth and efficient animation and point cloud rendering
- Optimised for ruggedised, touchscreen tablets for easy in-field use
- Desktop mode for reviewing data in the office.
- See the heading, inclination and activity of the animated C-ALS probe at all times
- Real-time surfacing and volume calculation from raw scan data for the production of closed 3D models and volumes
- Quickstart mode with single-click project setup up and instrument auto-detection
- Save live footage from the C-ALS camera
- Integration with third-party packages with the ability to import and export formats, such as LAS and DXF



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# **C-ALS Probe dimensions**





### C-ALS

Laser module				Physical data		
Laser classification (BS EN 60	825-1 : 2014)			Construction		Ma
(21 CRF 1040.10 and 1040.11 e pursuant to Laser No 50, dated	except for deviations d 24 June 2007)	Class 1		Water and dust resistant		IPE
Туре		InGaAs laser diode		Operating temperature range	Probe	-10
Wavelength (typical)		905 nm		5	Surface Unit	0 °
Resolution		1 cm		Dimensions	Probe	110
Maximum range to a passive	target*	Up to 150 m			Probe with exten-	21
Minimum range		0.5 m			sion piece	
			-		Surface Unit	27
Angle measurement				Weight	Stainless steel probe	5.9
Туре		Opto-electronic encoder			Single-section steel	3 k
Inertial Pitch-Roll Sensor		± 0.2°			extension piece	
Angular Accuracy		0.2°			Main C-ALS cable	0.1
Angular Resolution		0.1°			1 m Boretrak rod	0.4
Range	Vertical	-90° to 90°			Surface Unit	4.1
	Horizontal	0° to 360°		External power input		12
Motion		Servo-driven gear system in both axes with manual clutch override system	s	Power consumption durin	g scan	0.8

Physical data		
Construction		Machined aluminium and stainless steel
Water and dust resistant		IP67
Operating temperature range	Probe	-10 °C to +60 °C
	Surface Unit	0 °C to +50 °C
Dimensions	Probe	1100 mm × Ø50 mm
	Probe with exten- sion piece	2179 mm × Ø50 mm
	Surface Unit	270 mm × 245 mm × 170 mm
Weight	Stainless steel probe	5.9 kg
	Single-section steel extension piece	3 kg
	Main C-ALS cable	0.18 kg/m
	1 m Boretrak rod	0.4 kg
	Surface Unit	4.1 kg
External power input		12-15 V dc and 110-240 V ac
Power consumption during	scan	0.8 to 2.0 A

#### **Boretrak Sensors**

Type (standard system)	Triaxial sensor
Pitch-and-roll accuracy	± 0.2°
Pitch-and-roll range	360°
Compass (optinal) accuracy	<u>±</u> 1.2°

\* Max measuring ranges are recorded against Kodak white card (90% reflectivity).

For further information and the best possible application and performance support please contact Carlson at lasermeasurement@carlsonsw.com

# Merlin Vessel-Based Laser Scanner

Merlin is the marine Lidar (Light Detection and Ranging) system developed specifically for cost-effective and safer coastal, offshore and inland waterway surveying. Extremely robust, portable, and well-engineered, Merlin provides eye-safe, long-range laser scanning that enables the capture, processing, and analysis of geospatial point cloud data quickly and accurately.

# Safer, faster, more efficient surveying with Merlin

Seamless integration with existing echosounder technology enables the fast and effective acquisition of time-tagged survey data above and below the water simultaneously.

# Map the full environment in a single survey

Information acquired by Carlson's time-tagged Merlin marine laser scanner combines seamlessly with bathymetric echosounder data for complete datasets that reveal the full landscape above and below the waterline in the same survey.

Obtaining a full 360° point cloud with Merlin quickly and safely:

- Speeds up project timescales,
- Minimizes the amount of time crew spend in potentially hazardous areas, and
- Reduces the surveying costs associated with complex vessel-based surveying assignments.

# **Key Features**

- IP66 (EN 60945) water and dust resistance
- 250 m laser range (maximum)
- ±1 cm laser accuracy
- 360° field of view

# **Key Benefits**

- Saves on setup: Seamless integration with existing hardware and software means no need to duplicate equipment, infrastructure, or technologies already owned.
- Minimizes training costs: The low maintenance plug-and-play Merlin system is easy to install and operate, eliminating the need for specialist training. It is also compatible with industry-standard software packages.
- Improves worker safety: Fast installation, deployment, and speed of data capture reduce the amount of time spent in potentially hazardous marine environment.





CLASS 1

LASER PRODUCT







plate ensures rapid installation coastal erosion by comparing new and deployment

The custom-made mounting Accurately manage and monitor The portable Merlin laser scanner and old data with ease.

can be deployed for offshore surveying in remote locations.

# Safe, flexible, and easy to operate for a wide range of applications

Merlin is ready to install out of the box with no customization required. The mounting plate can either be permanently welded into place or attached temporarily to a mast or cabin roof by three simple screws.

Merlin's 250 m range\* addresses the challenges of safely and accurately mapping the full landscape above the waterline - including the shoreline, coastal features, manmade structures, and more - as it enables accurate data acquisition from a safe distance. These challenges include avoiding hazardous natural features and dealing with unpredictable weather conditions.

Merlin also comes with its own diagnostic tool, which can be used to set up the system with existing infrastructure, such as port numbers and IP addresses. It also enables operators to select and test a timing source and troubleshoot.

\* Passive range limit is target (reflectivity) dependent (to a 90% reflective target where the entire laser spot falls upon the target).



Merlin supports faster and more accurate data collection, minimizing the amount of time operators need to spend in the field



The marine surveying industry needs a dedicated marine laser scanner for high-performance data acquisition in extreme environments.

# Many uses for Merlin's high-quality 3D data

- Monitoring coastal change by comparing old and new information
- Creating navigation charts without venturing into hazardous coastal zones
- Updating risk management and flood models to predict future events by using • historic data
- Assisting with urban planning with identification of key marine features
- Collecting detailed information safely and guickly from high traffic waterways

#### **Connect an additional sensor**

The option to connect a second Merlin unit via a specialized top-side interface box further helps to reduce project timelines and improve point cloud density. Benefits of deploving two Merlin units on one vessel include:

- Reducing the amount of shadowing encountered during scanning
- Enabling the capture of more points per second for more detailed datasets in a shorter amount of time
- Increasing the quality and quantity of scan data that can be captured, for improved decision making





The Merlin marine laser scanner provides high- With improved data you can better analyse the performance range accuracy and marine resistance. landscape for complex mapping projects with ease

and confidence.

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#### Merlin: Compatible with all major software

The Merlin vessel-based Lidar system quickly measures and records time-tagged georeferenced data points, which can then be calibrated and processed into a finished

point cloud by the following packages:

- HYSWEEP<sup>®</sup> multibeam collection and editing software from HYPACK<sup>®</sup>
- NaviScan and Kuda sonar and laser data acquisition software from EIVA
- QINSy hydrographic data acquisition software from QPS
- Teledyne PDS software for hydrographic survey and dredging operations



The processed point cloud can then be exported in formats such as LAS or XYZ into a CAD package such as Carlson Point Cloud, to Carlson P3D Topo to produce a 3D model, create surfaces, or to export to other file formats including DXF or DWG.

Merlin's universal interface ensures operator familiarity and ease of use.

Carlson Merlin Vessel-Based Laser Scanner					
Laser module					
Туре	InGaAs laser diode				
Wavelength (typ)	905 nm				
Accuracy*	<u>+</u> 1cm				
Maximum energy per pulse	0.461 µJ				
Beam divergence	2.25 × 1.5 mrads				
Range resolution	1 cm				
Maximum range to a passive target**	250 m				
Minimum range	0.5 m				
Lens aperture size and location	28 mm (location at front of module)				
Scanner field of view	360°				
Scanner angle resolution	Up to 0.01°				
Scan rate	Up to 20 Hz				
Beam footprint at 50 m	141 mm × 103 mm				
Pulse measurement rate (points per second)	36000				
Power	11 to 30 V dc 198 W				
Physical data - Carlson Merlin					
Weight (Merlin unit excluding mount)	12.5 kg				
Dimensions (L $\times$ W $\times$ H)	370.5 mm × 274 mm × 423 mm				
Physical data - Carlson Merlin LT					
Weight (Merlin unit excluding mount)	8.4 kg				
Dimensions (L $\times$ W $\times$ H)	285 mm × 273.6 mm × 310 mm				

## **Merlin vs Merlin LT**

Two varieties of Merlin offer alternative configurations depending on your vessel setup.

The standard Merlin incorporates a GPS receiver which provides internal timing for the laser. This timing can also be exported to other equipment on the vessel.

The Merlin LT is a stripped down version of the Merlin. It is designed without the GPS receiver and also without the cabin-mounted interface box which provides a cabling interface and power management for the standard Merlin.

Lighter and more compact, the Merlin LT can be used on smaller, unmanned vessels and for installations where the timing is being imported from another part of the navigation system.

## **Global support and training**

Carlson provides expert training and support provided by our team of in-house surveyors and engineers at your location or at our offices in the UK, USA, Canada, and Australia. We also offer remote diagnostics support to perform instant software and hardware diagnostics from our offices to yours anywhere in the world. Please contact us at lasermeasurement@carlsonsw.com for more information.

Environmental	
Water and dust resistant***	IP66 (marine grade)
Operating temperature	-10 °C to +50 °C
Storage temperature	-25 °C to +70 °C
Tests and approvals	
CE conformity	DoC available
Safety of laser products (Class 1)	BS EN 60825-1: 2007 (21 CFR 1040.10 and 1040.11 except for deviations pursuant to Laser No. 50, dated 24 June 2007)
EMC	BS EN 60945: 2002 section 9-11
FCC compliance	CFR47 Part 15.19, 15.21, 15.105
Photobiological safety of lamps and lamp systems	BS EN 62471: 2008
Safety of machinery	BS EN ISO 12100: 2010
Safety of electrical equipment	BS EN 61010-1: 2010

\* Max measuring accuracy recorded at 50 m against Kodak white card (90% reflectivity) to 1σ. Accuracy is defined as the degree of conformity of the measured sample mean range to its actual (true) value, measured with reference to a total station under Carlson test conditions.

\*\* Max measuring ranges are recorded against Kodak white card (90% reflectivity).

\*\*\* Environmental protection is tested in accordance with EN 60529: 1992 + A1: 2002 and EN 60945: 2002.

# Quarryman<sup>®</sup> Pro

The Carlson Quarryman Pro is the 3D laser-scanning system of choice for quarries around the world. It is intuitive to use, portable and rugged, and carefully designed and tested to make it robust enough to operate in the toughest environments.

# Improves safety. Increases profitability. Made for the demanding quarry environment.

- Safe, long-range reflectorless surveying for blast planning, stockpile measurement, and whole site mapping
- Easily operated by one person, with very little training needed to use the system or the associated intuitive software
- Durable and reliable in tough environments certified water and dust resistance with operating capabilities from -20 °C to +45 °C
- Light and portable for easy, one-man operation that can quickly be moved around and between sites by operators
- Scans entire rock faces in minutes as it measures and records thousands of data points, which can be sent directly to a USB drive
- Provides a manual point-and-shoot mode and an automatic laser-scanning mode (250 points per second) and can be integrated with blast design software packages and with Lidar data collected from mobile mapping systems and UAVs
- Processes the collected data to create detailed 3D models, which can be edited, analyzed, and exported to specialist packages or other CAD software

# Blast design, optimization, and evaluation

Scan a full rock face quickly with the Quarryman Pro and then use the data to plan:

- More accurate blasts, which eliminates the costs associated with over-using explosives
- Safer blasts that keep workers safe
- Legally compliant blasts, which have less impact on the external environment by minimizing noise and vibration
- Blasts with optimal fragmentation, which cuts transport costs for quarried rock and minimizes the waste associated with over-fragmentation
- Improved floor control, minimizing wear on tires and heavy mobile equipment



# **Detailed mapping**

Use Quarryman Pro data to measure bench heights, level of crest and toe, slope angle, and maximum/minimum burden. This detailed mapping of a rock face increases safety as it enables the determination of actual burden across the face. This helps to avoid the problems associated with underestimating the burden, such as vibration and oversized rock, and overestimating the burden, which can result in flyrock and airblast.

# **Plan blast layout**

Determine the layout of the blast hole pattern using data from the Quarryman Pro, taking into account safety parameters, vibration limits, explosives to be used, and design floor elevations. The resultant blast design plan will specify the collar elevations, burden, spacing, drill hole diameter, type and quantity of explosives, and type and delay of detonations.



Quarries around the world rely on **Quarryman Pro** to plan safer, quieter, more effective blasting operations.



Perform safer, quieter, more effective blasting using data acquired from **Carlson** laser systems.

# Drilling

Utilize Carlson Boretrak® borehole deviation tool to check that drilling has been carried out correctly as per the blast design, verifying the hole depth, heading, and inclination, to increase safety and improve final results.

# **Features and Applications**

The must have on-site system for quarries for more than three decades, the Quarryman Pro has transformed on-site safety and improved post-blast workflow and minimized costs.

# 3D Map entire quarry or mine site

Fast, portable and rugged, the Quarryman Pro system provides scans that can be stitched together for a complete model of a site or for a quick and simple way to conduct necessary stockpile and volu- metric surveys. The long range of the Quarryman Pro minimizes the number of instrument setups required and also reduces the operator time needed to complete surveys.

Utilize the Quarryman Pro to compile a complete 3D map of a constantly evolving, openpit site to plan such operations as truck routes, siting of generators, crushers, or other equipment, and to report to local residents or other stakeholders at update meetings.

The Carlson Quarryman Pro offers the following features:

- A highly visible, full color sun-readable screen
- Data is saved to a USB for ease of data transfer, and enables holding many more files
- A GPS mount is built into the handle so that the Quarryman Pro can be geopositioned quickly, and easily maps point cloud data to other quarry surveys
- Minimal clicks for each operation greatly enhances work speed
- Auto date and time stamping helps users find files without needing to enter details.
- The battery issues a warning when low, but shuts down automatically if not recharged, retaining data for retrieval later
- The lightweight Li-ion battery provides at least four hours of scan time



Quarryman Pro is dust-resistant and waterproof for performance even in extreme conditions



When used in combination with our **Boretrak** borehole deviation tool, **Quarryman Pro** enables the design of more productive blasts.



Rock faces that are mapped by **Quarryman Pro** allow users to plan effective operations.

## **Quarryman® Viewer Software**

The intuitive Quarryman Viewer software offers increased flexibility and functionality as it speeds workflow:

- Clear, precise visuals enable quicker interpretation of data
- Automated point coding, traverse processing, and surfacing of single scans save time
- Ability to store most commonly completed functions makes it quick and easy to retrieve them for future projects
- Project tree gives easy access to, and control of, all data: scans, surfaces, observations, and stations
- Versatile import and export options together with user-preset filters reduce operator programming time



Quarryman software provides clear visuals for quicker interpretation of data.

L Import L Import ப் Export L Export Import Export Da Single Scan .dxf Points Multiple Scans 🕨 las. Surface .laz Selection pts Project .ptx .raw

Filters can be defined to obtain the data required. Data is then exported in multiple formats to all major CAD and point cloud packages.

	Quarryman Pro	Quarryman Pro LR (long range)				
Laser module						
Laser classification (BS EN 60825-1: 2014) (21 CFR 1040.10 and 1040.11 except for deviations pursuant to Laser No. 50, dated 2 June 2007)	Class 2	Class 3R*				
Infrared laser module						
Туре	InGaAs lase	er diode				
Wavelength (typical)	905 n	m				
Maximum energy per pulse	2.88 µJ	4.81 µJ				
Beam divergence	2.25 x 0.15	mrads				
Resolution	1 cm	ı				
Maximum range to a passive target **	Up to 750 m	Up to 1200 m				
Minimum range	10 m	20 m				
Lens aperture size and location	46 mm (location at	46 mm (location at front of module)				
Visible laser module						
Туре	InGaAsP las	er diode				
Wavelength (typical)	650 n	m				
Maximum power	<0.6 mW (continuous wave)					
Lens aperture size and location	3 mm (location at front of module)					
Angle measurement						
Encoder type	Opto-electron	ic encoder				
Encoder accuracy	0.02	0.02°				
Encoder resolution	0.01	0				
Range Vertical	-45° to -	+90°				
Horizontal	0° to 3	60°				
Motion	Stepper-driven worm a both axes with manu	and wheel drives in al clutch override				

Keyboard and display	
Display	3.5-in, sun-readable TFT
Resolution	320 x 240
Keyboard	17-button keypad
Data logging	
Supplied logging media	8GB USB drive
Compatibility	USB 2.0 and 3.0
Power	
Supplied battery	14.4 V Lithium-ion
Capacity	6.2 Ah
Scan time (typical)	210 min
Alternative power	12 V dc lead acid
Physical data	
Construction	Machined aluminium
Water and dust resistant	IP66
Operating temperature range***	-20 °C to +45 °C
Weight Including tribrach	8 Kg
Including tribatch and battery pack	8.6 Kg
Including transit case and accessories	16.5 Kg

Visible and invisible laser radiation. Avoid direct eye exposure.

\*\* Max measuring ranges are recorded against Kodak white card (90% reflectivity).

\*\*\* Visible laser module operational -10°C to +60 °C

# Boretrak Rodded and Cabled

The Boretrak measurement system measures borehole deviation in a wide range of applications, including quarrying, mining, geotechnical, and engineering works.

# **Improve safety**

Accurately measure the borehole data needed and effectively use the data to plan projects safely and in compliance with audit trail.



- Provides 3D data on drilling activity from ground level or underground site
- Ensures compliance with quarrying legislation
- Avoids the potential risks and costs associated with deviated or unsurveyed boreholes

# **Increases work efficiency**

Optimizes blasting and engineering works by easily creating detailed maps of drilling activity.



- Easy-to-use with minimal training, lessening the need for an expert surveyor
- Reduces the need for large teams with entire drilling sites able to be measured and modeled in hours
- Portable, lightweight and made to be transported, the easy-todeploy system is designed to be used by a single operator
- Audits drilled holes and produces reports in minutes, making on-site drilling operations data-led, with no guesswork and data gaps

# Works reliably in extreme environments

The rugged, portable design, which is resistant to weather and environmental factors, make Boretrak a system for challenging projects.



- Provides a high degree of environmental protection to perform reliably and accurately in the toughest conditions
- Rodded Boretrak operates in areas of magnetic interference and in flooded holes

# **Carlson LMD Blast Design Package**

Widely used in mines, quarries, and in various engineering and geotechnical works, the Quarryman Pro laser scanner, Boretrak, and Blast Commander software make up the Carlson blast design package. The Boretrak system is used alongside the Carlson Quarryman Pro to provide detailed data at all stages of blast planning, thus providing quarry managers with a greater degree of control over final results.

#### Get accurate data on site and make better decisions

- A ruggedized PDA interfaces with dedicated PC software so users can audit drilled holes and produce reports in minutes. Results can then be issued to drillers on site if needed. On-site drilling operations are then data-led, responsive and better integrated.
- Map entire sites. Boretrak data can easily be georeferenced and related to your local co-ordinate system helping users to map entire sites. This means current results can be compared with historical data and data viewed from a range of systems – notably Carlson's Quarryman Pro – in one place. There's no guesswork and no data gaps.
- Allows uphole and downhole borehole measurement with a single tool.







The Boretrak system enables faster yet safer rock face blasting.

**Cabled Boretrak** 

Carlson's Cabled Boretrak system is The quick-to-deploy Boretrak is designed for supplied in a Peli-case that can be use by a single operator. hand carried by a single operative.

Compact, lightweight, rugged, and highly portable, Cabled Boretrak enables users to work quickly and move across large sites, covering vast areas, without the need to transport bulky surveying equipment.

- Designed to be deployed downhole on its integrated toughened cable to depths up to 65 meters (70+ yards)
- Contains a dual axis tilt sensor and digital compass to calculate borehole deviation from the collar position at fixed intervals
- Simple, robust CDU provides speedy job configuration, calibration, survey, and download

#### **Rodded Boretrak**

The Rodded Boretrak system uses specially designed rods to deploy the probe: these maintain the orientation of the system without the need for a compass. This method offers accurate measurement for uphole deployments and areas that contain ferrous material, whether next to cabling or metalwork, or where there is magnetic interference.

The Rodded Boretrak system is ideal if needed to be deployed to great depths. Cabled probes limit users to the fixed cable length originally purchased. With Rodded Boretrak, additional stacks of rods can simply be added to be deployed down deeper holes.

#### **Recent Rodded Boretrak improvements include:**

- Bluetooth communications between the probe and ruggedized PDA, negating the need for a hotshoe and enabling easy, on-site data download
- The ruggedized PDA provides the ability to communicate wirelessly with the probe and allows data to be sent to a PC via WiFi or Bluetooth
- The Boretrak Mobile Android app provides on-site viewing and troubleshooting, and enables users to output data directly into their own third-party packages
- Store and revisit multiple projects on one device
- Android capabilities and applications further complement the Rodded
  Boretrak system
- New smaller and lighter briefcase-style transit case

# **Increase safety and efficiency**

#### Measuring borehole deviation

Drilled holes are employed in a wide variety of quarrying and mining projects and need to be drilled to a specified depth, inclination, and heading. Deviation from these specifications can pose real dangers and also increase costs due to unpredictable blast results. The Carlson Boretrak provides a reliable way of measuring borehole deviation by taking the actual results of drilling activity into account. When used as part of the blast design package, this ultimately saves mine and guarry owners on secondary breakage.



The benefit of a Cabled Boretrak is speed and portability.

transport, explosives, and fuel costs as well as increasing worker safety and that of others working or living near blast sites.

#### Work safely

- Deployed from ground level (or from underground sites), Boretrak keeps workers safe while providing 3D data on drilling activity
- Boretrak works with Quarryman to help ensure compliance with quarrying legislation, protecting local residents, employees, and property
- Measuring borehole deviation avoids the risks associated with incorrect borehole data: fly-rock caused by poorly designed blasts, or intersection with underground utilities in engineering works
- Safer, more efficient blasts also result in neater quarry faces and quarry floors, on which it is easier to operate machinery and vehicles

#### Work reliably and efficiently in extreme environments

- A high degree of dust- and water-proofing is engineered into both the Rodded and Cabled Boretrak variants. Resistance to wet weather, water-logged ground, submersion, temperature extremes, sand and dust mean that Boretrak performs reliably and accurately in tough conditions.
- Portable, lightweight, and easy to transport across sites and between locations, the easyto-deploy Boretrak is designed to be used by a single operator. The Cabled Boretrak system comes in a single 'Peli' case, with a total weight of less than 11 pounds (5 kg), and a soft case to carry the tripod and ballast rod when needed. The Rodded Boretrak probe and rods can also be hand carried by a single operator.



Rodded Boretrak's rods guide and locate the probe.

# **P3D Boretrak plug-in**

Carlson's P3D software is a point and surface modelling and processing package. Functionality for the Cabled and Rodded Boretraks is offered as a plug-in to P3D.

Available free of charge as part of all new Boretrak system purchases, the Boretrak P3D plug-in enables you to use the Boretrak 'out of the box' with no need to purchase additional third-party software. The package offers functionality for downloading, processing, editing, and viewing Boretrak data. The processed holes can then be exported in a wide range of data formats and comprehensive printed reports can be generated. The combination of Boretrak hardware and the P3D Boretrak plug-in provides operators with the control required to complete complex tasks.

P3D Boretrak plug-in works with all generations and models of Boretrak system, including seamless data transfer in DRL format with the 'Boretrak Mobile' Android application which is supplied with Carlson's latest Rodded Boretrak. DRL data can be transferred across Carlson's range of mining, quarrying and surveying software packages.

P3D's UI is very flexible and you can adapt the workspace to create a clear and simple interface for Boretrak operations.



The powerful 3D graphics window shows all surveyed holes together with the relevant design data.



Each hole can be positioned on predefined coordinates. These can be automatically generated by default, or you can import surveyed or planned hole coordinates from a file. Alternatively, the Hole Designer allows you to manually create individual holes or rows of holes. Any hole coordinates can then be automatically matched to the surveyed holes on import of Boretrak data.

	tion		_		_		Front View	Side View	
Hole Colla	r S		•	Hole Data	Survey	Data 1	-		_
Rod Azim.	/th	180.00°					•		
lesign —							51	Surveyed Points Drill Hole Designed Hole	
Indination		0.00°					.0	1	
Depth		24.00 m					-1.2		
Azimuth		180.00°					-2.4	1	
housed							-3.6		
Az	Inc	Depth	Dev	x	Y	z	-4.8		
	-	0.00	0.00	1020.00	1000.00	1000.00	-6.0	1	
166.068*	15.762°	2.00	0.54	1020.13	999.47	998.08	-7.2		
173,404*	16.684*	4.00	1.12	1020.20	998.90	996.16	-8.4	1	
170.195*	16.670*	6.00	1.69	1020.29	998.34	994.24	-9.6	1	
							-10.8		
_							-12.0		
							-13.2	4	
	<ul> <li>Sum</li> </ul>	reyed Point	s = Desig	ned Hole	Drill Hole		-14.4		
			<u></u>	00			-15.6		
			5	.25			-16.8		
			3	.50			-18.0	H	
	200		Ţ	.75			-19.2	₽ <del> </del> <b>↑</b>	
	2/01			.00	190		-20.4	·	
							-21.6	s <del> </del>	
			1						

You can create design holes in P3D Boretrak plug-in and then export these in DRL format to Boretrak Mobile. This will then form the basis of your Boretrak project in the field which, in turn, can then be downloaded back into P3D.

Select Row 1										<ul> <li>New Row</li> </ul>	F	tename Row	Delete Ri	ow
						Holes								
Hole ID	x			Y		z		Azimuth		Inclination		Dep	th	^
1	12345678.12 m	÷	213456	78.43 m	÷	-1201.12 m	÷	1.00*	*	5.00*	÷	25.00 m	\$	
2	12345683.43 m	:	213456	90.13 m	:	-1201.17 m	:	1.00*	•	5.00*	:	25.00 m	:	1
3	12345688.74 m	÷	213457	01.84 m	+	-1201.22 m	÷	1.00°	*	5.00°	:	25.00 m	:	
4	12345694.05 m	÷	213457	13.54 m	÷	-1201.27 m	÷	1.00*	*	5.00*	÷	25.00 m	\$	
5	12345699.36 m	:	213457	25.24 m	:	-1201.32 m	:	1.00*	•	5.00*	:	25.00 m	:	1
6	12345704.67 m	÷	213457	36.95 m	+	-1201.37 m	÷	1.00°	*	5.00°	÷	25.00 m	:	
7	12345709.98 m	•	2134574	48.65 m	•	-1201.42 m	÷	1.00*	*	5.00*	÷	25.00 m	:	
8	12345715.29 m	:	213457	50.36 m	÷	-1201.47 m	:	1.00*	+	5.00*	:	25.00 m	\$	
9	12345720.60 m	÷	213457	72.06 m	•	-1201.52 m	•	1.00°	*	5.00°	÷	25.00 m	:	
10	12345725.90 m	•	213457	33.76 m	•	-1201.57 m	÷	1.00*	*	5.00*	÷	25.00 m	\$	
11	12345731.21 m	:	213457	95.47 m	:	-1201.62 m	•	1.00*	•	5.00*	:	25.00 m	:	].
						Hole General	ion							
Start X 1000.00 m		_	\$	Azimuth	0.0	0°	_	\$	Spaci	ng 5.00 m	_			٥
Start Y 1000.00 m			\$	Indination	0.0	0°		۵	Coun	1				٥
Start Z 1000.00 m			\$	Depth	10.	00 m		\$	Beari	90.00°				\$
						Generate								
													Anniv	

All data relating to each hole can be viewed on a single window showing design information, plan view, side views and each Boretrak reading in tabular form. Both the graphics and the table illustrate how the surveyed hole deviated from the design hole as the Boretrak was deployed.



# **Rodded Boretrak®**





Optional PDA	
Model	CEDAR CT5
Display	4.7" high-definition (720 mm × 1280 mm) with Corning® Gorilla® Glass 3
Interface	Capacitive touchscreen and buttons
Data communications	Bluetooth (probe to PDA), Wi-Fi and USB (PDA to PC)

\* Environmental compatibility requirements of EN 60529:1992+A1:2002.

\*\* The probe operating and storage temperature may be limited by the choice of battery. The supplied Duracell has an operating temperature of -20 °C to +54 °C and a storage temperature of +5 °C to +30 °C

# **Cabled Boretrak®**



Construction							
Probe	316 stainless steel body and brass insert						
Ballast Rod	Glass fibre and stainless steel						
Cable	Kevlar-reinforc	ed polyurethane					
CDU	Black acetal						
Physical	Weight	Dimensions					
Probe	2.5 kg	480 x 38 mm (L x Dia)					
Balast Rod	960 g	1000 x 38 mm (L x Dia)					
Cable	50 g/m	N/A					
CDU	800 g	210 mm x 102 mm x 41 mm					
Sensor							
Dual axis inclinometer	Range: +/- 40°	from the vertical					
	Accuracy: 0.2°						
	Resolution: 0.1°						
Compass	Range: 0 to 360	° from the vertical					
	Accuracy: +/- 1	' typical (vertical and calibrated)					
	Resolution: 0.1°						

CDU	
Display	$128 \times 64$ graphic backlit
Keypad	$4 \times 4$ plus dedicated Fire button
Memory	64 KB
Data download	RS232 (selectable baud rate)
Power system	
System	3 x 1.5V C (MN 1400, LR14) cells
Environmental	
Probe	Waterproof (pressure rated to 100 m)
CDU	IP66
Operating temperature	0 °C to +45 °C
Storage temperature	-10 °C to +50 °C

# **Void Scanner**

Laser-based cavity monitoring system

The affordable Carlson Void Scanner is a survey and inspection tool designed for use in extreme environments to work quickly, safely, and accurately. The specialized and ruggedized Void Scanner uses time-of-flight laser measurement to map the shape, position, and spatial location of cavities quickly, giving site managers the information needed to plan more profitable projects, improve operational efficiency, and, importantly, ensure high standards of safety in potentially hazardous locations.

# Applications for mining and civil engineering

Void Scanner solves a wide range of underground surveying challenges at a low cost, including the following:

- Gallery, void, and stope surveying
- Ore pass monitoring
- Mine design management
- End-of-shift extraction volume scanning
- Compliance, environmental, and safety management
- Underground blast planning
- Drive surveys
- Pre- and post-excavation mapping
- Storage silo volume measurement
- Project profitability/feasibility planning

# **Benefits of use**

Reach otherwise inaccessible or hazardous locations safely to determine the exact volume and position of air-filled underground spaces. This helps to provide:

- Enhanced safety Ensure the safety and compliance of current operations and future projects with Void Scanner's detailed models of underground voids
- Increased profitability Use Void Scanner to map the shape and dimensions of underground voids, thus helping to manage dilution and ore loss in the mine
- Better planning Support new project planning with Void Scanner's full 3D images of sites that can be exported into CAD packages to plan for new extraction, installations, or mine workings



## **Engineered for precise, safe underground use**

#### **How Void Scanner works**

The Void Scanner laser sends out infrared pulses, which reflect off solid surfaces and are received back into the probe to provide quick, precise, and safe surveying of underground voids. Distance measurements are accurate to  $\pm 5$  cm and the encoders measuring the direction of the laser are accurate to 0.2°.

The scan information is corrected by internal pitch-and-roll sensors to produce realtime XYZ coordinates for each data point. This allows the data to be accurately geo-referenced in the mine's co-ordinate system and multiple scans can be stitched together. The output data can then be plotted against design drawings or as-built data to build a 3D representation of the project site.

#### **Specialized features**

#### Ease of use

Quick set-up and simple operation – it takes 5 minutes to unpack the system, connect cables, mount to the boom, and ready the software – speeding regular stope volume calculations.

#### Speed of operation

Complete a full scan in 1° increments in less than 12 minutes with the 200 points-per-second scan rate, 360° horizontal scan, and vertical scan extent of 270°.

#### Flexible deployment

Mount the Void Scanner via tripod, boom, mast, and crane to enable safe operation where access is limited or dangerous.

#### **Optional wireless connectivity**

Control the Void Scanner wirelessly from a position of safety (up to 50 meters if needed) with the optional WiFi box that includes a rechargeable battery, a wireless module, two power options, and a ruggedized IP65 Peli<sup>™</sup> case enclosure.

#### Multi-station project capabilities

Scan from multiple locations and view the resulting 3D data together in real time for a complete 3D representation of a mining or construction project site.

#### VS Software - Intuitive design and navigation

Running on a rugged field PC or tablet, Carlson's Cavity Profiler – VS package controls the Void Scanner, guiding users through deployment and processing and enabling visualization of scans in real-time as data is collected. This saves time both in training of operators and when in use on-site.

The software's post processing tools enable operators to analyze, edit, and filter data as required. Geo-referenced point clouds or modeled surfaces can be exported in a number of industry-standard formats for easy integration with third-party processing software packages.

#### Tested to guarantee high performance

Developed for use underground, Carlson's Void Scanner has been subjected to rigorous environmental testing to guarantee high performance operation within specified limits of temperature, pressure, humidity, mechanical stress, and other adverse environmental conditions. Testing includes IP65 dust and water protection and performance in extremes of temperature and humidity. Inspections also include:

- Shock testing
- Acceleration testing
- Vibration testing & drop testing



#### **VOID SCANNER dimensions**





Void Scanner	
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#### Laser module

Laser classification (BS EN 60825-1: 2014) Class 2\* (21 CRF 1040.10 and 1040.11 except for deviations pursuant to Laser No 50, dated 24 June 2007)

#### Infrared laser module

Туре	InGaAs laser diode
Wavelength (typical)	905 nm
Maximum energy per pulse	1.06 µJ
Beam divergence	2. 76 x 1.5 mrads
Resolution	1 cm
Maximum range to a passive target••	Up to 150 m
Minimum range	0.5 m
Lens aperture size and location	18 mm location at front of module

#### Visible laser module

Туре	InGaAs laser diode
Wavelength (typical)	650 nm
Maximum power	<0.6 mW
Lens aperture size and location	3 mm location at front of module

Angle measurement		
Туре		Opto-electronic encoder
Accuracy		0.2°
Resolution		0.1°
Range	Vertical	+ 135° to -135°
	Horizontal	0° to 360°
Motion		Servo-driven gear systems with manual clutches
Pitch-and-roll sensors		
Туре		Accelerometer based
Pitch-and-roll accuracy		+ 0.2°
Pitch-and-roll range		360°
Physical data		
Construction		Machined aluminium and stainless steel
IP degree of protection•••		IP65
Operational temperature range		-10 °C to 45 °C
Transit case dimensions		620 mm x 480 mm x 240 mm
Weight		Probe: 5 kg / System in transit case: 23 kg
External power input		10 to 15 V dc and 110 to 240 V ac
Power consumption durin	ng scan (typical)	9.6 W

\* Viewing laser output with optical instruments designed for use at a distance (e.g. binoculars) may pose an eye hazard.

\*\* Max measuring ranges are recorded against Kodak white card (90% reflectivity).

\*\*\* Environmental compatibility requirements of EN 60529:1992+Al:2002.

# Void Scanner Wi-Fi Box





Dimensions given in mm



#### Void Scanner Wi-Fi Box **Physical data** IP65 (when lid is closed and connector IP degree of protection\* caps fitted) Operational temperature range -10 °C to +45 °C -20 °C to +50 °C for up to one month Storage temperature range\*\* (thereafter -20 °C to +35 °C) Dimensions 260 mm x 198 mm x 109 mm Weight 2.0 kg Power Internal battery 14.4 V dc, 6.8 Ah lithium-ion battery **External battery** Optional Carlson-supplied 14.4 V dc, 6.8 Ah lithium-ion battery pack Max current 3.15 A Max power rating 45.4 W T3.15 AH 250 V Fuse **Operations Connection to Void Scanner** Via power/data cable: supplied 1.5 m cable or standard 13.6 m cable Data connections Wi-Fi connection to PC or handheld tablet RS232 connection to Void Scanner probe Continuous scanning time (typical\*\*\*) 6 hours on internal battery Wi-Fi range (limit) >50 m line of sight Charge time 3 hours (approx.) **Charging temperature** +10 °C to +45 °C Compatibility Mk3 onwards Void Scanner probe Wi-Fi frequency range 2.412 GHz-2.484 GHz Wi-Fi standard 802.11 b/g/n

\* Environmental compatibility requirements of EN 60529:1992+A1:2002.

\*\* Storage at up to 50 °C permissible within guidelines. Prolonged storage at high temperatures

Windows versions 7, 8 and 10

Cavity Profiler - VS: version 1.3 onwards

will dramatically shorten life.

**Operating system** 

Software

\*\*\* Under standard test conditions.





Several **FiX1** units can be configured into a single system. One unit acts as the master, with up to eight slaves connected to it. All the slaves are accessed and controlled through the master unit.

The **FiX1** is not limited to volumetric data. At its simplest it will output a volume at the end of any scan. However, it also stores a timestamped archive of the collected point clouds which can be downloaded via the numerous connection options. This allows the **FiX1** to be used as a standard laser scanner.

# **Advantages of the FiX1**

- · Automated delivery of volumetric data
- Provides stockpile volume information or detailed scans in geographically remote areas without assigning man power and measurement tools.
- After installation, **no knowledge of surveying, data processing or point cloud** manipulation is required by users.
- **Improves safety** by removing the need for feet on the ground in potentially hazardous areas, such as quarries or open pit mining.
- Identify trends in material stockpiling or usage.
- Multiple units can be **connected in a network** to allow monitoring of large stockpiles or distinct unrelated locations within a site.
- Web interface accessible through cellular, Wi-Fi or ethernet.
- **Resolution of scans** can be adjusted to meet time requirements. A fast, low resolution scan can be completed in 5 mins. Slower, high resolution scans can take 25 mins.
- Versatile mounting plate supplied for easy installation.
- Options to mount the unit hanging down or sat upright.
- **Serial and USB ports** provide opportunities to interface with external sensors for more advanced configurations.
- Rugged design for durability in extreme conditions:
  - IP67
  - Temperature range of -40 °C to +50 °C.
- **GPS/GLONASS** for site location and identification.



Carlson

# How it works – System

- A common web interface is provided across the three connectivity options, Cellular, Wi-Fi and Ethernet.
- The web interface presents a **complete history of scans and volumes** that the user can download, if required.
- Scheduled scans can report completion and volumetric data via email and SMS.
- The web interface provides **access to all settings and diagnostics** such as scheduling of scans, system performance, laser and motor configurations.
- **Fault reporting** can be accessed through the web interface and alerts sent to email.
- The software for the FiX1 is **remotely upgradeable** through the web interface.
- In a multiple system configuration, the master provides the connection to all networked systems so that they can be configured and accessed through a single interface.



# How it works - Volumetric Data

- If a volumetric scan is activated the FiX1 will generate a point cloud, extract the region of interest and calculate the volume of material in that area. The volume is presented to the user through the web interface without any need for further manipulation.
- Volumes can be verified by examining the linked point cloud data for foreign objects and anomalies.
- Volumetric accuracy can be user-defined through the setting of laser and angle resolutions in the web interface.
- The web interface provides a graphical representation of how volumes have changed over time.
- Data for a multiple FiX1 system is automatically stitched together based on references created during installation and therefore a total volume can be calculated without the need for manual intervention.

# How it Works – Laser Scanning

- By default, all **point cloud data is stored in the FiX1**. This information can be downloaded from the FiX1 in the common '.las' format.
- Like the volumetric calculations, **the resolution of point cloud data** can be configured through the web interface.
- **Automatic stitching** of the point clouds in a multiple scanner system is carried out by the referencing of each FiX1 during installation.
- **Point clouds** for distinct and isolated FiX1 systems in a multiple scanner setup can be downloaded in isolation through the FiX1 master.
- Pont cloud **manipulation and processing** can remain 'invisible' to the user for regular operations.





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# **Carlson FiX1**

# **Dimensions**



Laser module
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Туре	InGaAs Laser Diode
Wavelength (typical)	905 nm
Accuracy*	<u>+</u> 10 mm
Maximum Energy per Pulse	0.461 uJ
Beam Divergence	2.25 x 1.5 mrads
Range Resolution	10 mm
Maximum Range to Passive Target**	250 m
Minimum Range	0.5 m
Lens Aperture Size and Location	28 mm located in tilt head
Beam Footprint at 50m	141 mm x 103 mm
Maximum Measurement Rate (points per second)	15000 Hz

#### **Physical Data**

Size	(H x W) 495 mm x 314 mm (rotational clearance 368 mm)
Weight	12.5 kg
Power	85 – 265 VAC, 80 W

#### Environmental

Water & Dust Resistance	IP67
Operating Temperature	-40 °C to +50 °C
Storage Temperature	-40 °C to +85 °C

Angle Measurement	
Туре	Opto-electronic Encoder
Angular Accuracy	0.0055°
Pan Angle Resolution	0.0055°
Tilt Angle Resolution	0.0055°
Pan Range	360°
Tilt Head Range	360°
Scanning Field of View (Pan)	360°
Scanning Filed of View (Tilt)	200°
Motion	Servo controlled Brushless DC Motor
External Connections	
Serial	Rugged 9-Pin D-Type
Ethernet	Rugged RJ45
USB	Rugged STD USB A Female
Antenna	3 x 50Ω SMA (IP67)
Power	4-pin Rugged Binder Connector
SIM Card	Access via IP67 threaded plug
Connectivity	
Serial	115200 baud, with 12 V, 1 A power. Isolated data and power.
USB	Full Speed USB2.0 with 5 V, 500 mA isolated power.
Ethernet	10/100 Base T
Wi-Fi	<ul> <li>802.11 b/g/n 1x1 (1-14, max channel width 20 MHz)</li> <li>Up to 72.2 Mbps OTA throughput, 50 Mbps actual throughp</li> </ul>
Cellular	<ul> <li>2G: GSM/GPRS/EDGE (multi-slot class 10) note: only EDGE RX mode supported</li> <li>Quad band support (GSM850/E-GSM900/w DCS1800/PCS1900)</li> <li>3G: WCDMA (HSDPA 21Mbps cat14 / HSUPA 5.76Mbps cat6)</li> <li>Quad band support (band 1 / 2 / 5 / 8)</li> <li>Class3 power class</li> </ul>
GNSS	• GPS/GLONASS receiver • Assisted GNSS • SBAS: WAAS, EGNOS
1 Sa	



\* Max measuring accuracy recorded at 50 m against Kodak white card (90% reflectivity) to 1 $\sigma$ . Accuracy is defined as the degree of conformity of the measured sample mean range to its actual (true) value, measured with reference to a total station under Carlson test conditions.

\*\* Max measuring ranges are recorded against Kodak white card (90% reflectivity). Carlson Software maintains the right to change the specifications.

# By Surveyors, For Surveyors Carlson Works for You



www.carlsonsw.com

# The Complete Workflow

Offering powerful software, with comprehensive yet easy-to-use features, backed by dedicated customer service, Carlson is used world-wide by professionals in land surveying, civil engineering, construction, machine control, mining, crash/crime investigation, and agriculture.

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